



Object is $1\frac{1}{2}$ dia cylinder 3 inches tall
3d printed solid. pla

Robot must touch the back of the start area
Start at start box.
Drive to the object area.
Pick up object.
Carry object to the finish area.
Timer stops when robot hits the back of the finish area.
2 Runs are allowed. (or 5 minutes)
Fastest time wins.

Robots cannot drive over walls.
Robots must move object into the finish area.
The timer will stop when the robot enters the finish area.
Will be manually timed. (Stop watch)